

94. (New) The method as set forth in claim 41 wherein said step of establishing a fixed position reference coordinate representative of the initial start position of said medical implement includes establishing said reference coordinate in relation to the patient's body.
95. (New) The method as set forth in claim 94 wherein the reference coordinate of the implement is at a predetermined location of the patient.
96. (New) The method as set forth in claim 95 wherein the predetermined location is at an incision.
97. (New) The method as set forth in claim 95 wherein the reference coordinate of the implement corresponds to an internal site of the patient..
98. (New) The method as set forth in claim 97 wherein the reference coordinate of the implement corresponds to a site external of the patient.
99. (New) The method as set forth in claim 41 wherein the step of establishing a fixed position reference coordinate representative of the initial start position of said medical implement includes aligning an axis of the base point of the medical implement with an incision in the patient.
100. (New) The method as set forth in claim 41 wherein the step of determining includes performing a coordinate transformation from the base point to the active point of the implement.
101. (New) The method as set forth in claim 100 wherein the coordinate transform is a fixed transform less than 90 degrees.
102. (New) The method as set forth in claim 101 wherein the fixed transform is on the order of 45 degrees.